

Computing Beyond Turing

How neocortical theory can lead to machine intelligence

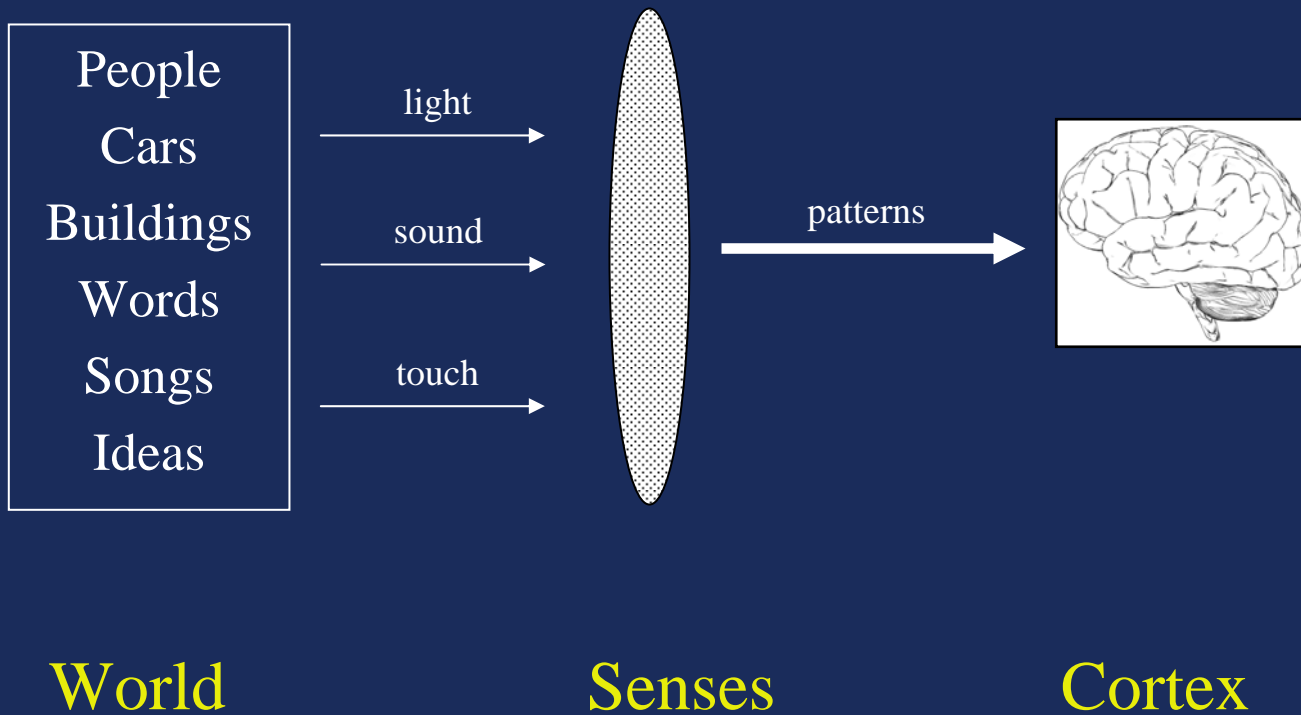
Stanford Computer Forum

April 15, 2009

Jeff Hawkins

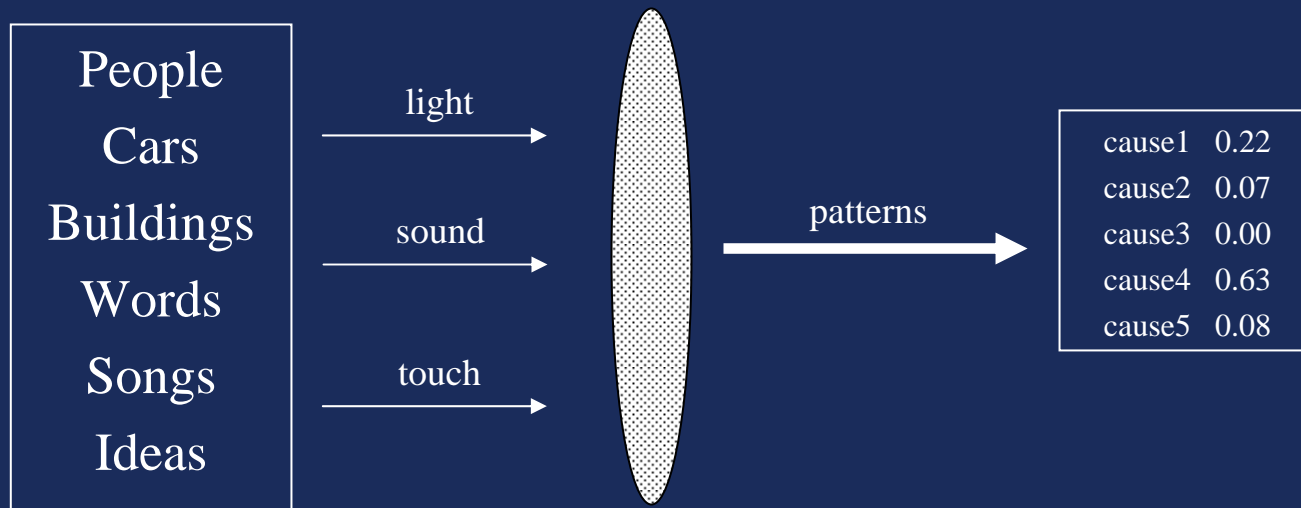
Numenta

What Does Cortex Do?



What Does Cortex Do?

- It builds a model of the world -

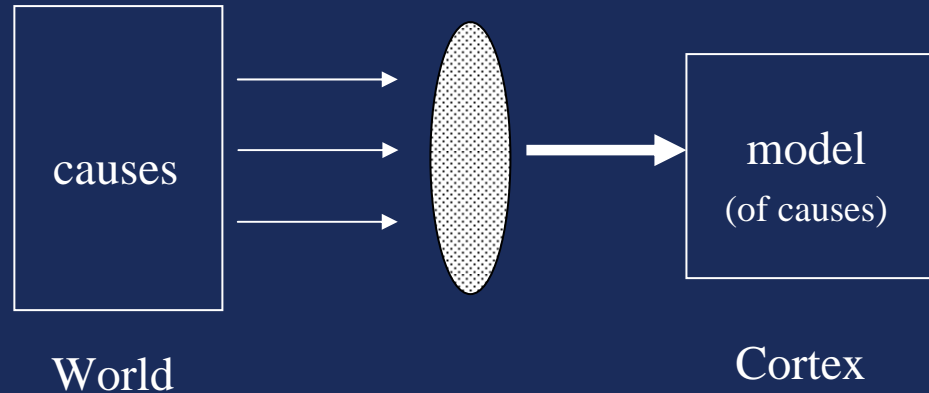


World
(causes)

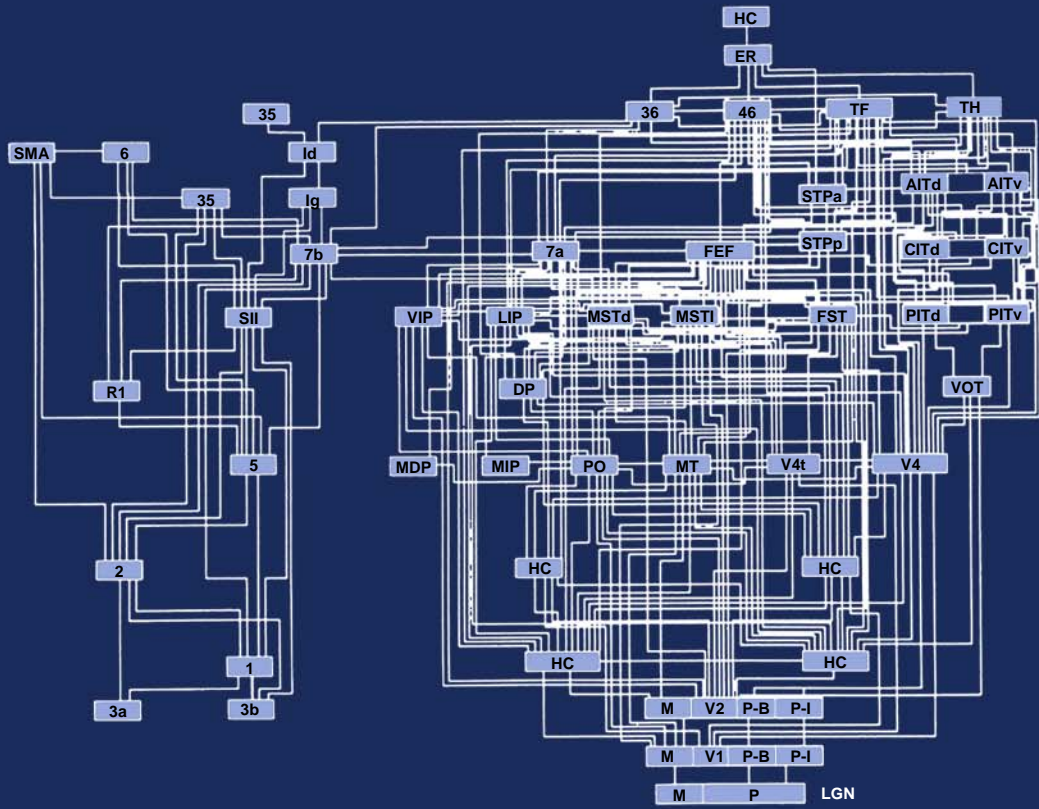
Senses

Cortex
(model of causes)

What Cortex Does



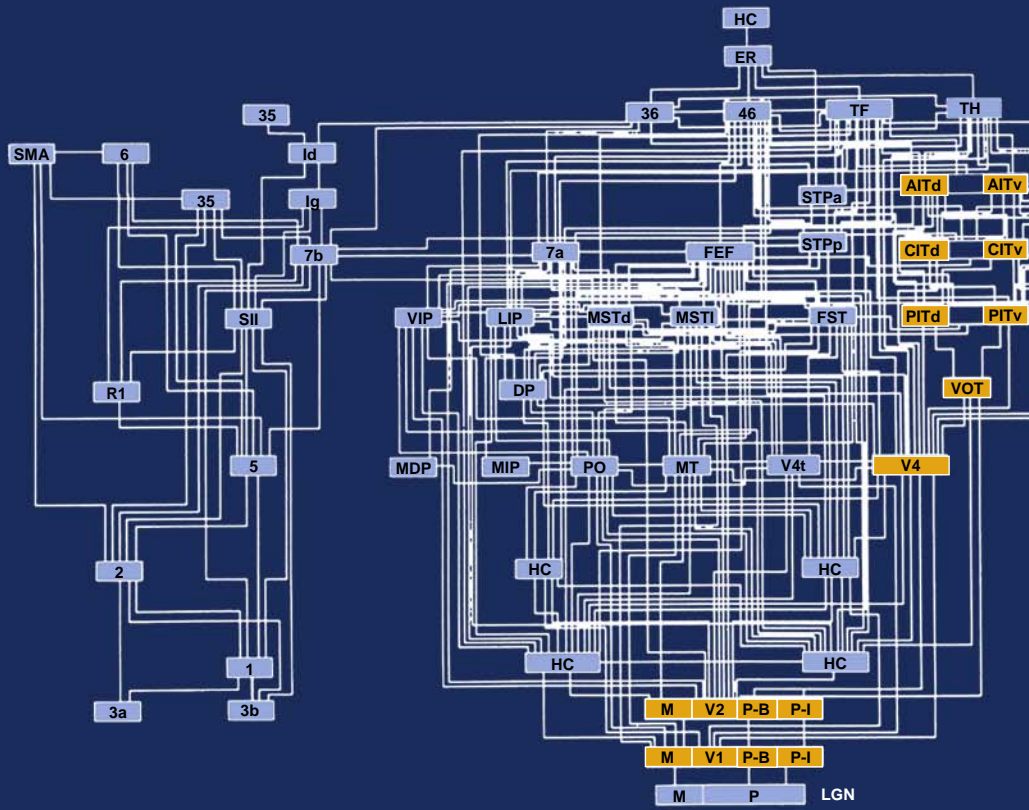
- 1 Discovers causes in the world
- 2 Infers causes of novel input
- 3 Predicts future
- 4 Creates motor behavior



- Knowledge is distributed hierarchically
- Self training through changing sensory patterns
- Each region is similar

Sensory data
(skin)

Sensory data
(retina)



- Knowledge is distributed hierarchically
- Self training through changing sensory patterns
- Each region is similar

Sensory data
(skin)

Sensory data
(retina)

46 TF TH

STPa

AITd AITv

7a FEF STPp

CITv CITd

VIP LIP MSTd MSTI FST

PITd PITv

DP VOT

MDP MIP PO MT V4t

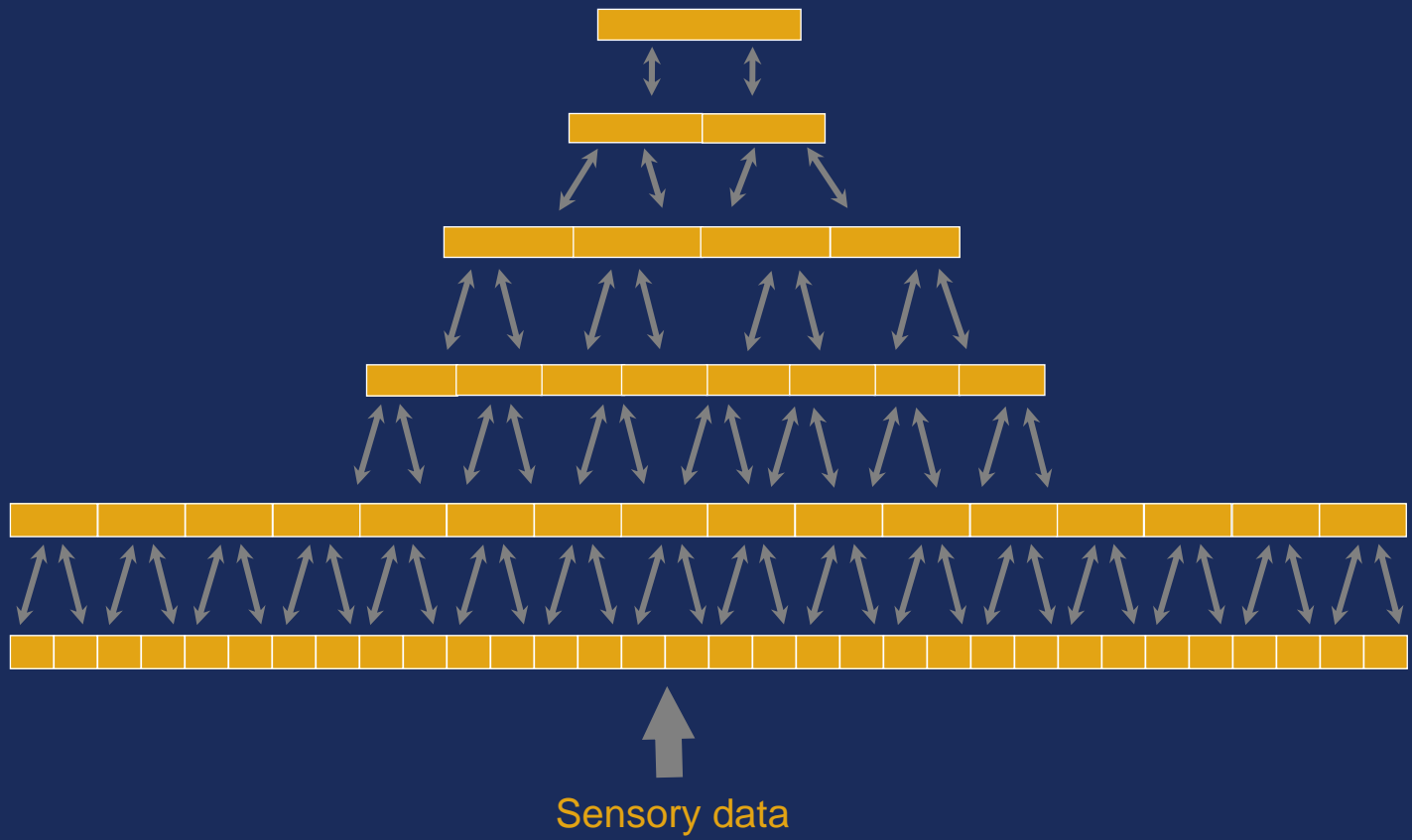
V4

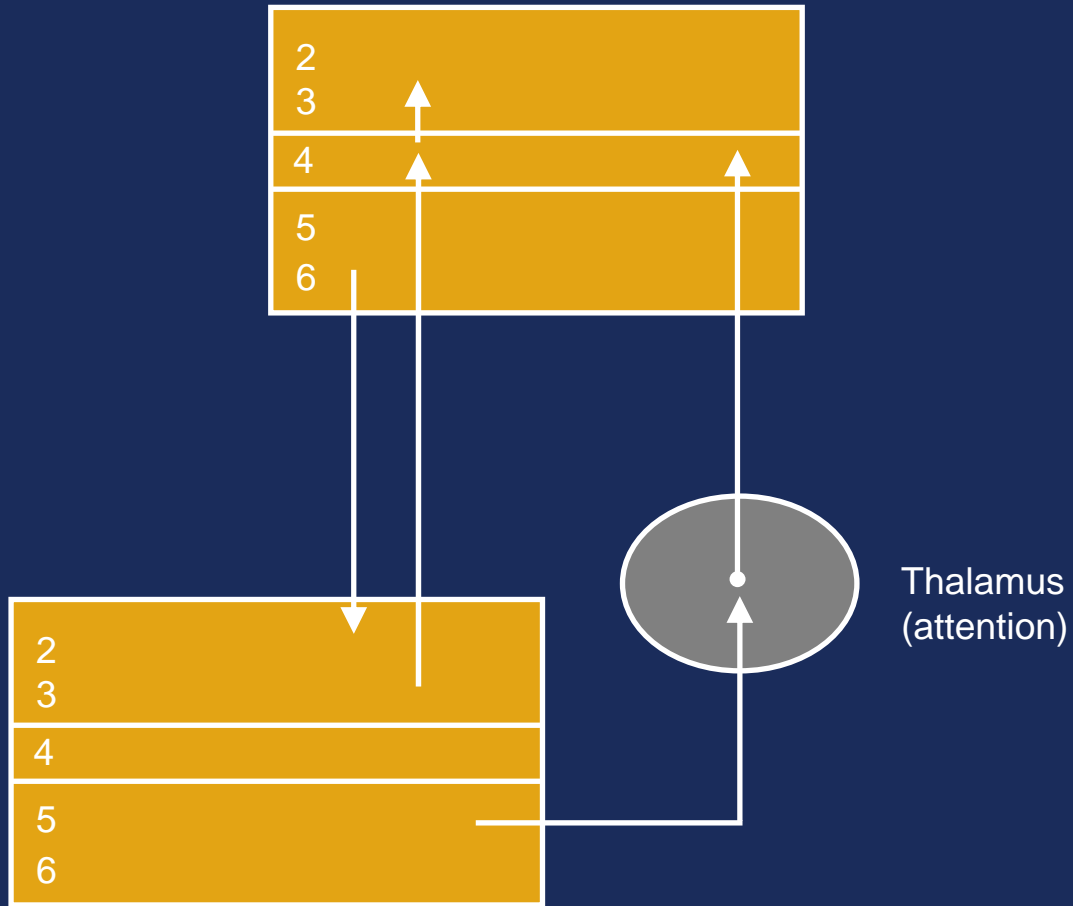
PIP

V3A

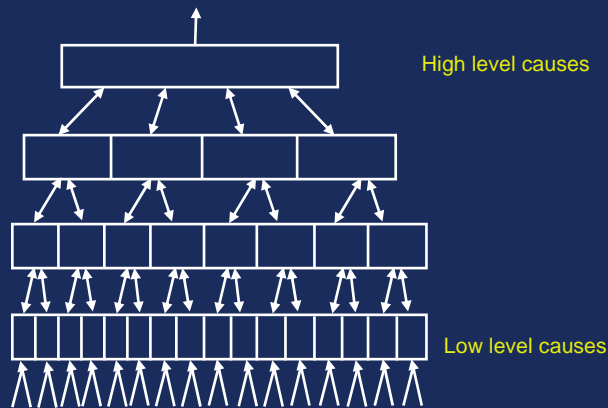
V2

V1





Hierarchical Temporal Memory



Each node

- Learns common spatial patterns
- Learns common sequences

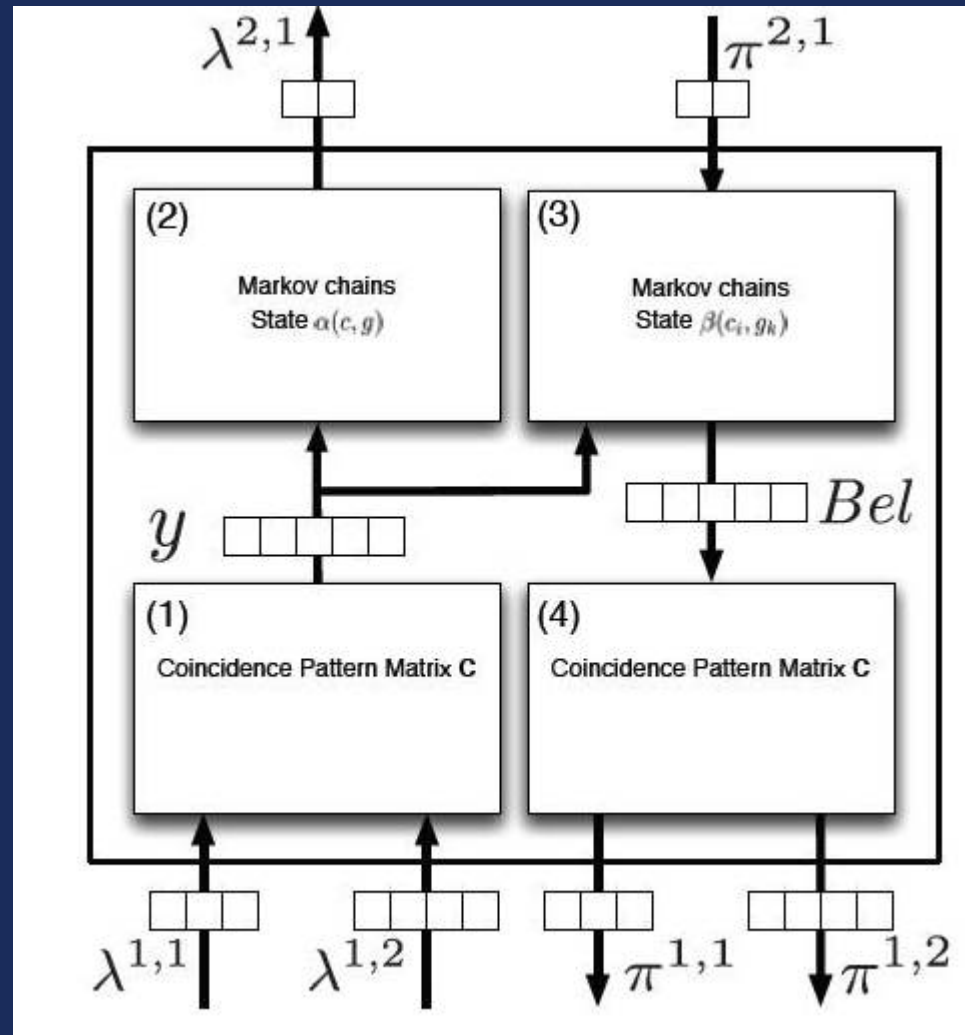
Sequence names passed up

Predicted spatial patterns passed down

Creates hierarchical model of causes

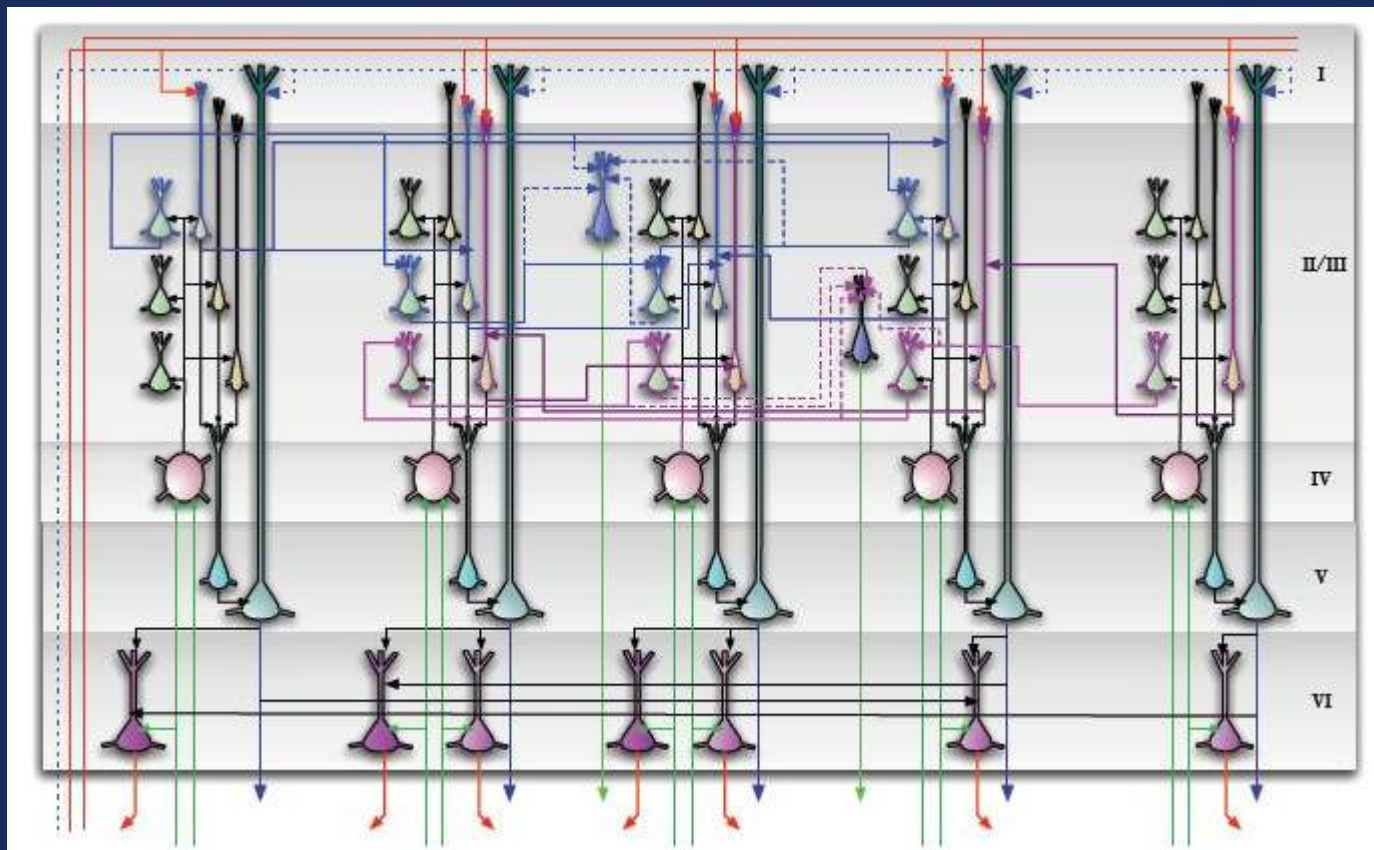
Bayesian methods resolve ambiguity

Belief Propagation In an HTM Node



Belief Propagation Equations In an HTM Node

<p>1) Calculate likelihood over coincidence-patterns.</p>	$y_t(i) = P(\neg e_t c_i(t)) \times \prod_{j=1}^M \lambda_t^{m_j}(r_i^{m_j}) \quad (4.1)$ <p>where coincidence-pattern c_i is the ∞-occurrence of $r_i^{m_1}$'th Markov chain from child 1, $r_i^{m_2}$'th Markov chain from child 2, \dots, and $r_i^{m_M}$'th Markov chain from child M.</p>
<p>2) Feed-forward probability over Markov chains (temporal groups) using dynamic programming</p>	$\lambda_t^k(g_r) = P(\neg e_0^k g_r(t)) \times \sum_{c_i(t) \in C^k} \alpha_t(c_i, g_r) \quad (4.2)$ $\alpha_t(c_i, g_r) = P(\neg e_t c_i(t)) \sum_{c_j(t-1) \in C^k} P(c_i(t) c_j(t-1), g_r) \alpha_{t-1}(c_j, g_r) \quad (4.3)$ $\alpha_0(c_i, g_r) = P(\neg e_0 c_i(t=0)) P(c_i(t=0) g_r) \quad (4.4)$
<p>3) Calculate the belief distribution over coincidence patterns</p>	$Bel_t(c_i) \propto \sum_{g_r \in G^k} P(g_r \neg e_0) \beta_t(c_i, g_r) \quad (4.5)$ $\beta_t(c_i, g_r) = P(\neg e_t c_i(t)) \sum_{c_j(t-1) \in C^k} P(c_i(t) c_j(t-1), g_r) \beta_{t-1}(c_j, g_r) \quad (4.6)$ $\beta_0(c_i, g_r) = P(\neg e_0 c_i(t=0)) P(c_i(t=0) g_r, \neg e_0) \quad (4.7)$
<p>4) Calculate the messages to be sent to child nodes.</p>	$\pi^{child}(g_m) \propto \sum_{i \in \mathcal{V}_i} I(c_i) Bel(c_i) \quad (4.8)$ <p>where</p> $I(c_i) = \begin{cases} 1, & \text{if } g_m^{child} \text{ is a component of } c_i \\ 0, & \text{otherwise} \end{cases} \quad (4.9)$

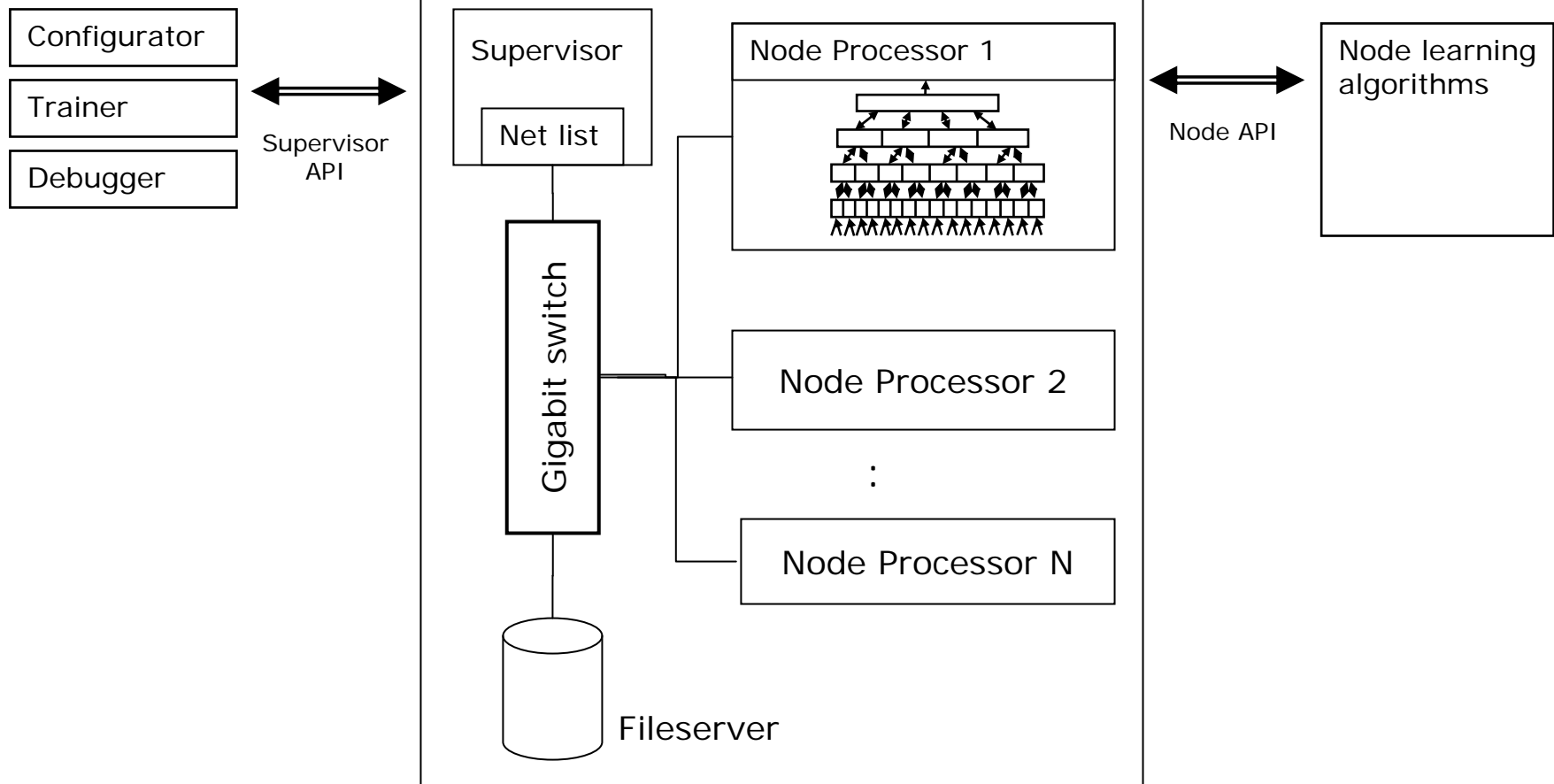


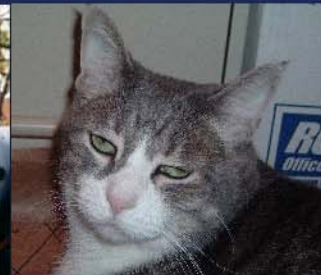
NuPIC, Numenta Platform for Intelligent Computing

2) Dev Tools

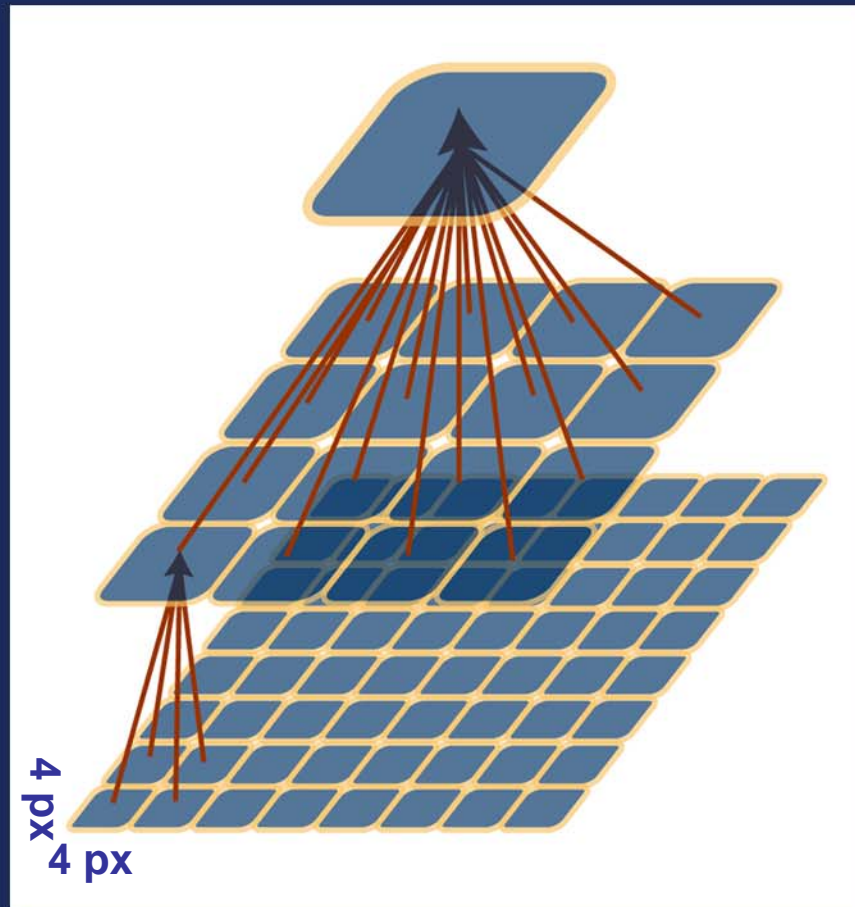
1) Run time environment

3) Learning Algorithms





Pictures: Simple Vision System (32 x 32 Pixels)


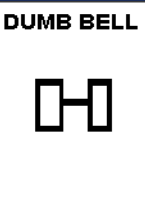

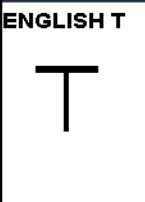
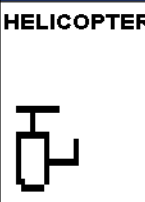

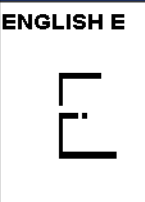
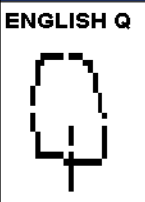

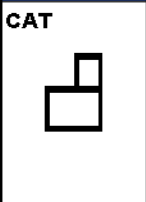


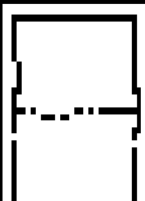
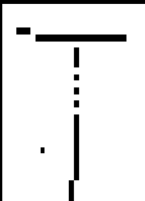

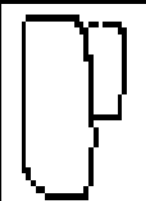


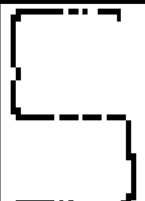
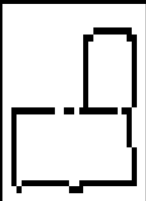


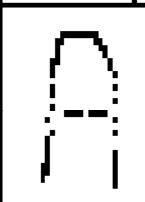
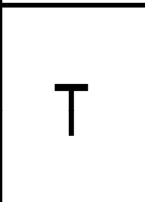
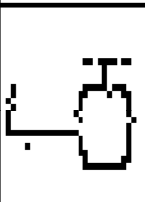



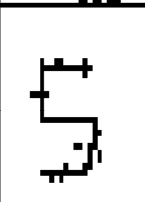
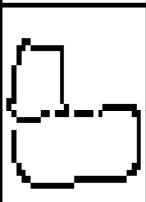












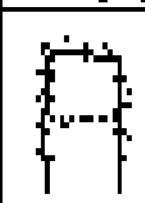



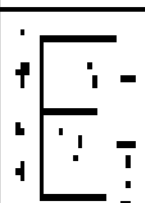


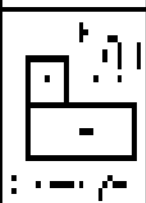


Level 3

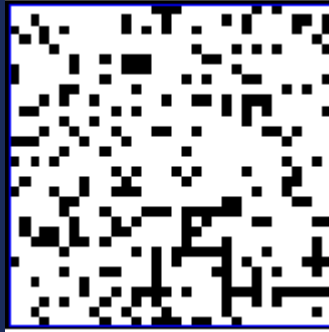
Level 2

Level 1

A	I	U	H	C	B
G	H	R	E		I
Q	R	F	S	P	B
田	Q	F	2	b	d
田	Q	田	Q	E	F
H	L	Q	Q	2	P
田	T	U		W	Q
田	Q	H	t	F	R

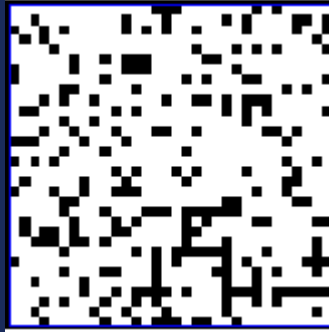
DOG	DUMB BELL	ENGLISH A	ENGLISH T	HELICOPTER	MUG	ENGLISH E	ENGLISH Q	ENGLISH S	CAT
									
									
									
									
									

Time Based Inference



Time Based Inference

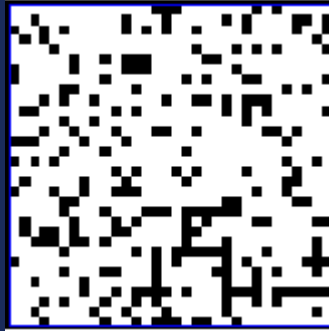
Static inference
(with noise)



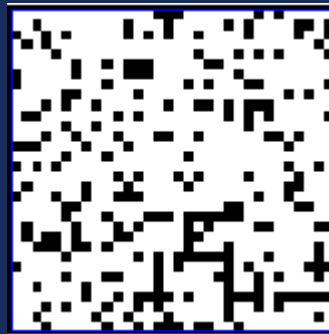
19%

Time Based Inference

Static inference
(with noise)

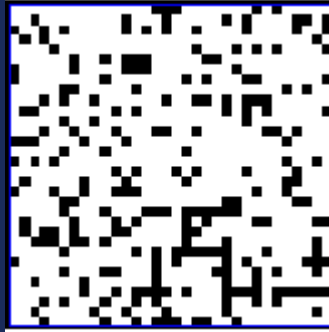


19%

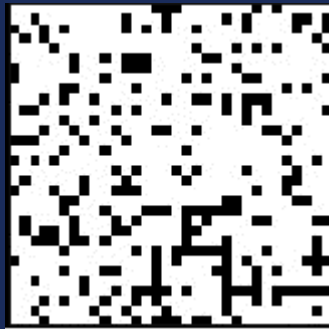


Time Based Inference

Static inference
(with noise)

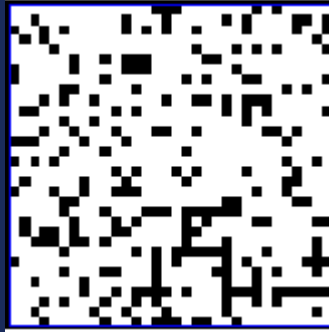


19%



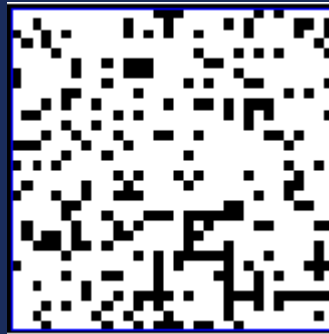
Time Based Inference

Static inference
(with noise)



19%

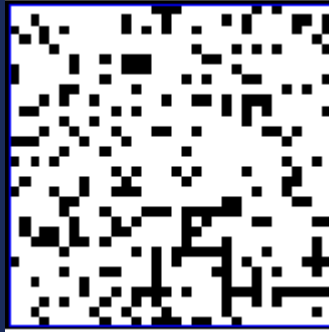
Time based inference
(with noise)



52%

Time Based Inference

Static inference
(with noise)

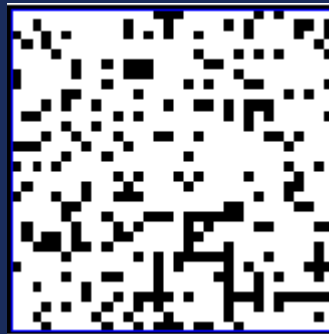


19%

Time based inference
(with noise)

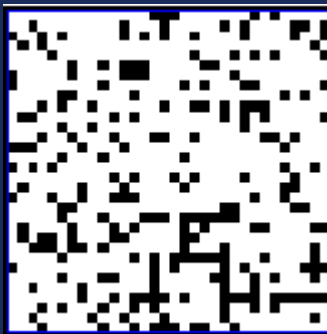


52%



Time Based Inference

Static inference
(static noise)



19%

Time based inference
(with noise)

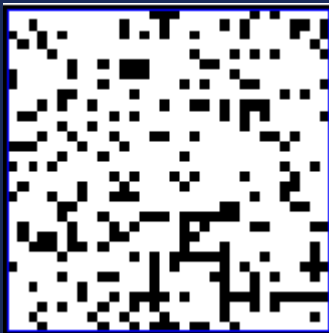


52%



Time Based Inference

Static inference
(with noise)



19%

Time based inference
(with noise)



52%

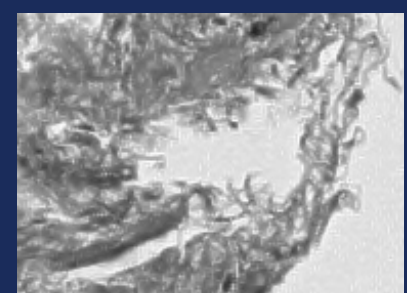
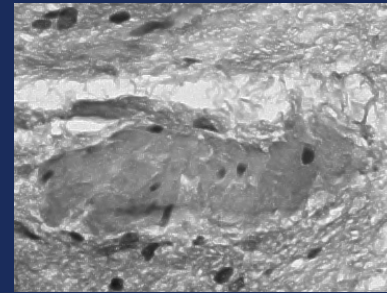
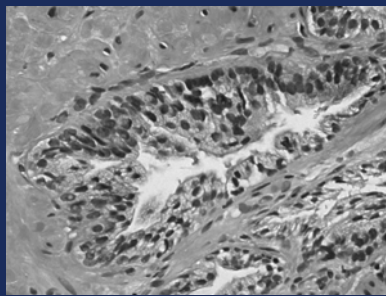
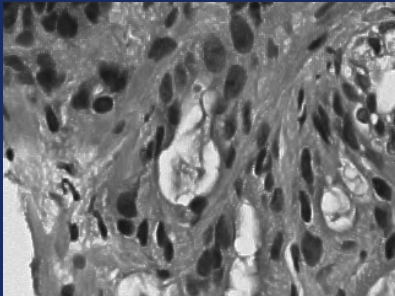
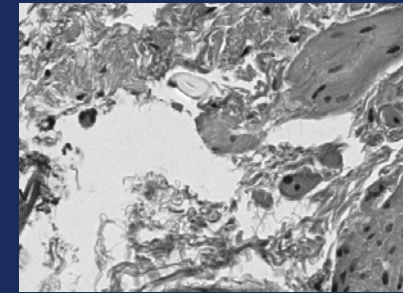
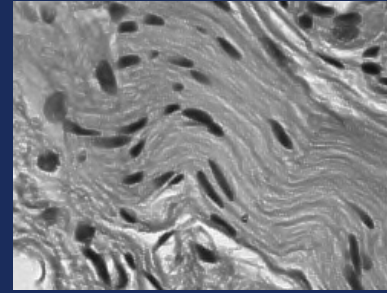
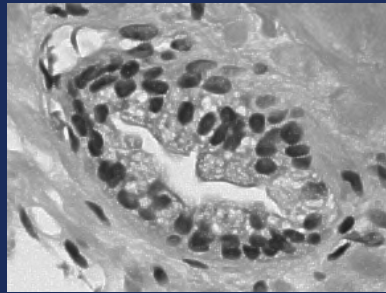
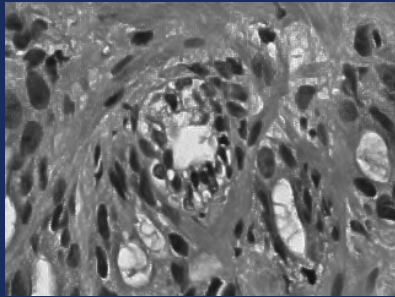
Time based inference
(with dynamic noise)



40%

HTM Vision In Digital Pathology

- discriminate glands from other structures -

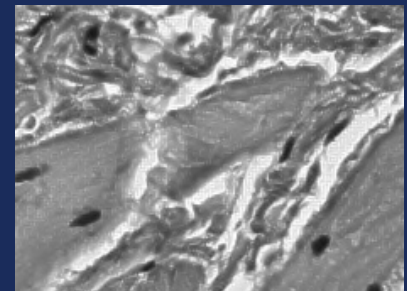
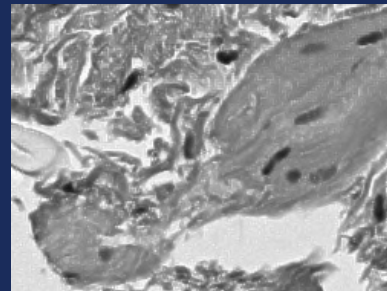
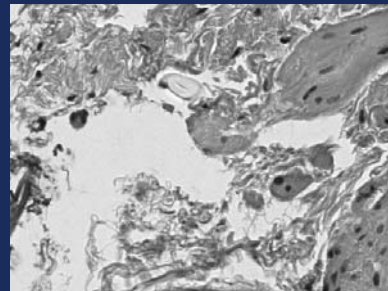
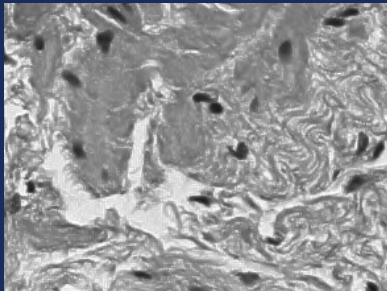


Glands

Not glands

Promising Early Results

- We trained a network to recognize glands
 - Training set: 195 images of glands and non-glands
 - Test set: 80 novel images
- Result: test set accuracy was 95%
- The four errors were “reasonable”

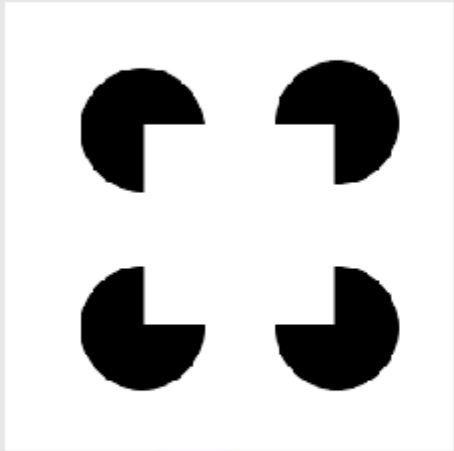




Illusory Contour

Numenta Vision Test App - Subjective1.png

Images

← → 📄 1 of 2







 



Recognize



Continuous Recognition



Distortions

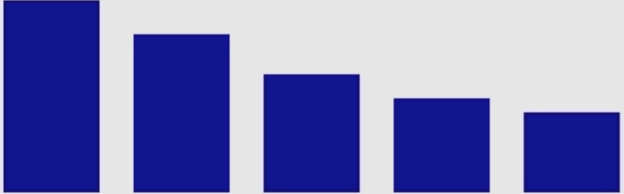
Undo

Revert

Results


attention/sr/subjectiveContours

Categories Inspect

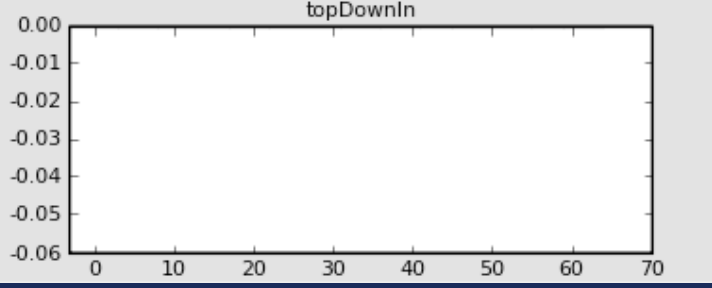
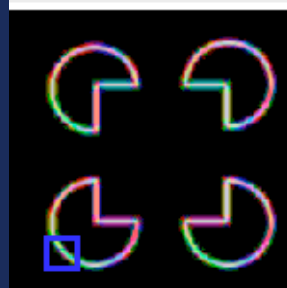
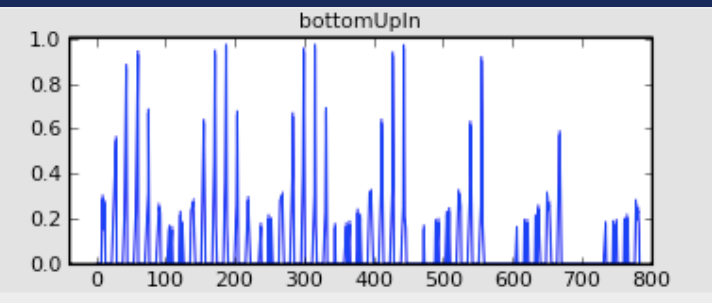
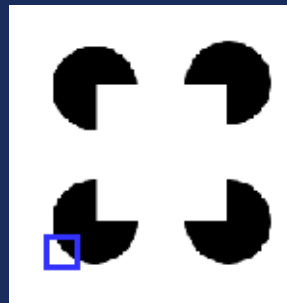
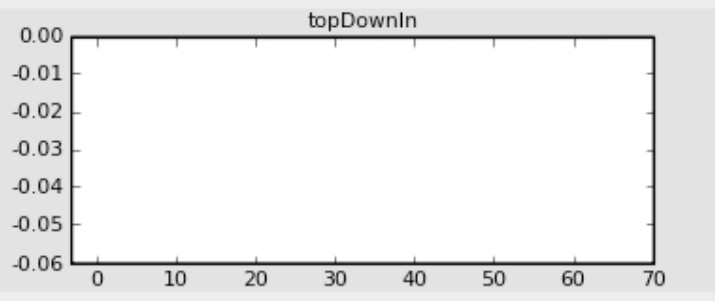
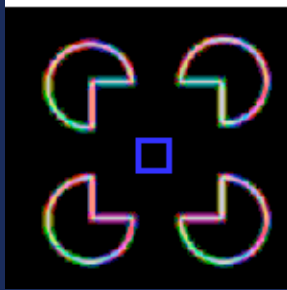
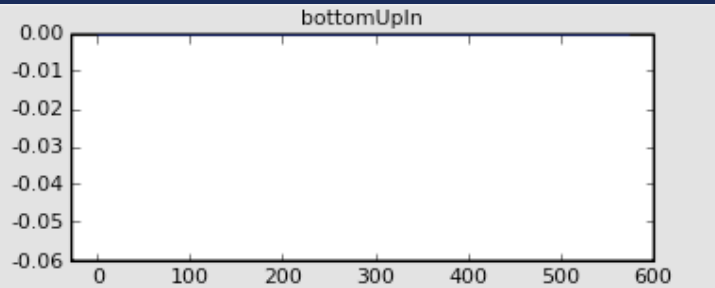
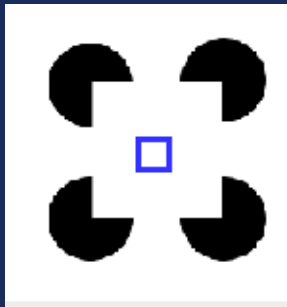


Category	Score
rectangle	High
cell phone	Medium-High
binocular	Medium
rubber duck	Medium-Low
car	Low

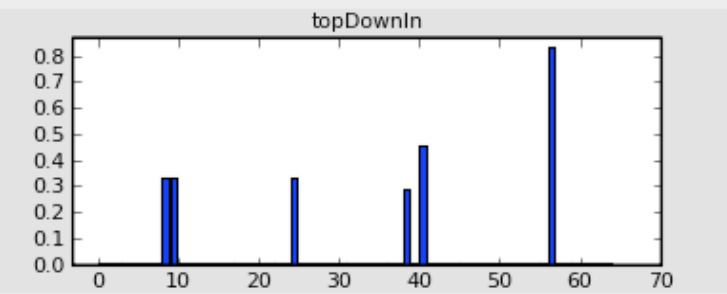
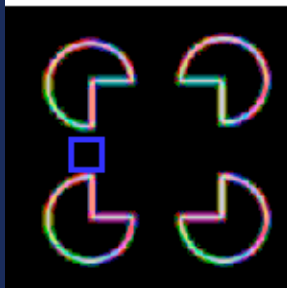
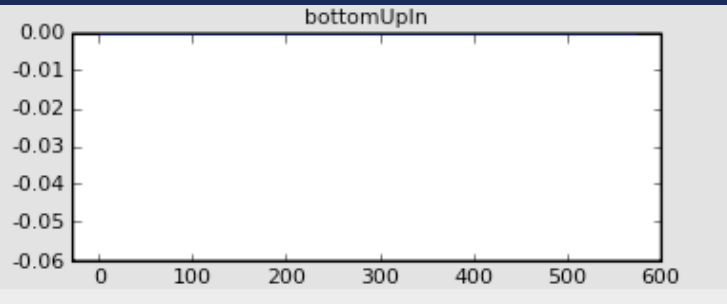
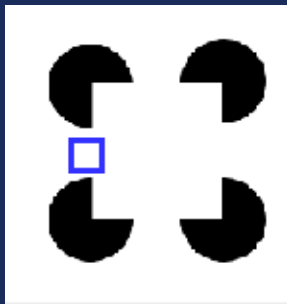
rectangle cell phone binocular rubber duck car



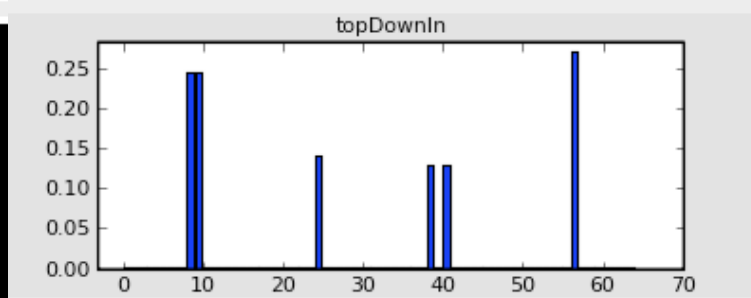
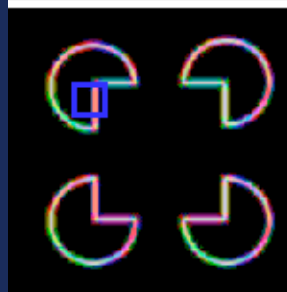
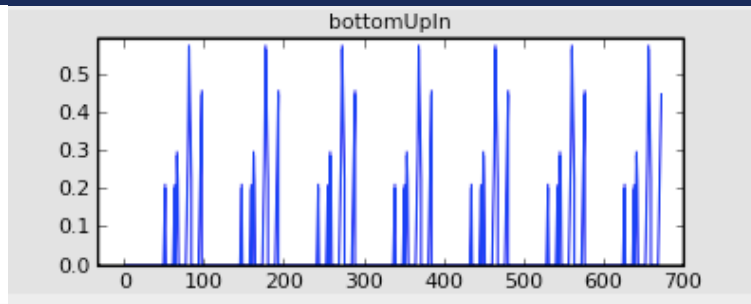
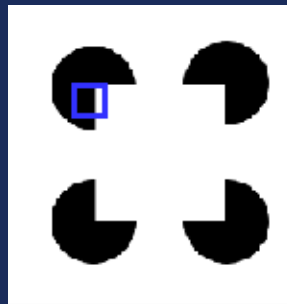
Illusory Contour



Illusory Contour



Perceived line
with no bottom up
support



HTM Application Areas

- Medical: Digital pathology
- Voice: Speaker/gender id
- Security: Video behavior recognition
- Auto: Lane change prediction

- Banking: Fraud detection
- Web: Analytics
- Pharma: Drug discovery
- Networks: Attacks and Failures
- Gaming: Motion capture inference
Visual object editor
- Semantic analysis of text

Technical Challenges

- Algorithms
 - Sequence Memory algorithms
 - Attention mechanisms
 - Feedback
 - Sensory pre-processing
- Performance
- Silicon vs. software

To Learn More

- Read “On Intelligence”
- Sign up for Numenta newsletter
- Download demo applications
- Download NuPIC
- Attend HTM workshop June 25, San Jose, CA
- Internships or employment at Numenta

- jhawkins@numenta.com



